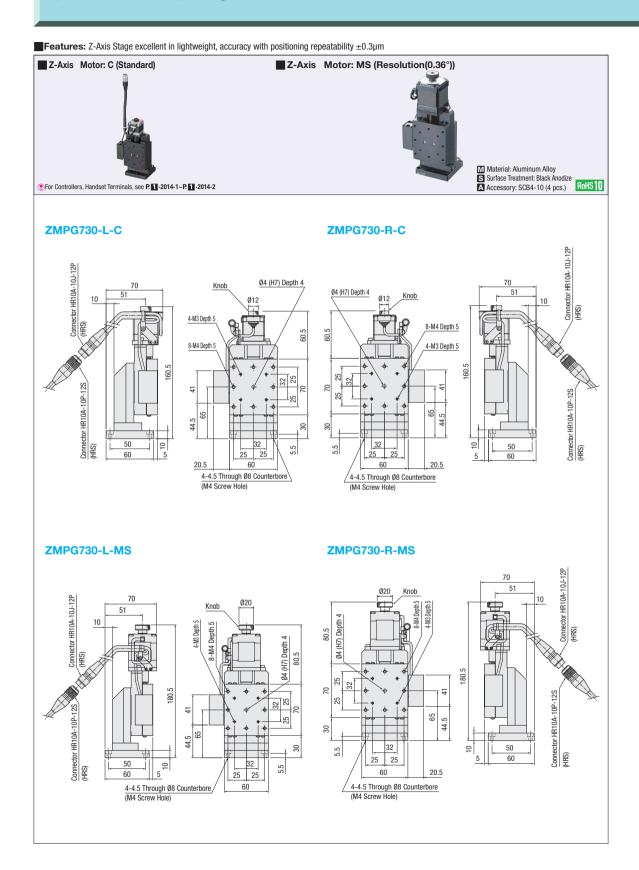
[Motorized] High Precision Z-Axis - Cross Roller





For CAD data, see the MISUMI website.

Part Number		Sensor			Mechanical Standards			Accuracy Standards *1		
Туре	No.	Cover Position	Motor	Cable	Stage Surface (mm)	Travel Distance (mm)	Weight (kg)	Unidirectional Positioning Accuracy	Pitching	Yawing
ZMPG 730	730	L (Standard)	C (Standard)	N (Cable not included	60×70 30	0.9	-5µm or less / Full Stroke	25" or less	20" or less	
ZWFG	730	R (Reversed)	MS (Resolution(0.36°))	(separately sold))	00×70	30	1.1	Jμπ οι iess / i un συσκο	23 01 1658	20 01 1655

Cable

*1. The above accuracy standards of Unidirectional Positioning Accuracy are for a single axis.





Configure Online

Continion Specifications				
Feed	Screw	Ball Screw Ø8, Lead 1		
Gu	ide	Cross Roller Guide		
	Full	2μm (1μm)*3		
Resolution *2	Half	1μm(0.5μm)*3		
	Fine Feed (upon 1/20 partitioned)	0.05μm		
Max. S	peed *4	20mm/sec		
Positioning	repeatability	Within ±0.3µm		
Load C	apacity	29.4N		
Lost N	/lotion	1µm or less		
Back	clash	0.5µm or less		
	htness	3µm or less		
Paral	lelism	30µm or less		
Motion P	arallelism	10µm or less		

	Full	2μm (1μm)*3
Resolution *2	Half	1μm(0.5μm)* ³
	Fine Feed (upon 1/20 partitioned)	0.05µm
Max. S	peed *4	20mm/sec
Positioning I	repeatability	Within ±0.3µm
Load C	apacity	29.4N
Lost N	/lotion	1µm or less
Back	dash	0.5µm or less
Straigl	ntness	3μm or less
Parall	lelism	30µm or less
Motion Pa	arallelism	10µm or less
10.771		

- *2. This represents the travel distance of stage per one pulse signal. *3. The values in () are for Motor Option MS (Micro Step).
- *4. This represents the max, speed that can be driven by the recommended controller switched to Full Step mode, with the max. load applied. (The value differs depending on the current driving controller and the current load) The value differs depending on the motor option.
 - The above specifications table is for a single axis stage placed flatly.

Connector Din Configuration

_	Connector Pin Configuration	tion
	1	10
	2	9
	3	8
	11	
	4	12
	5	_6_

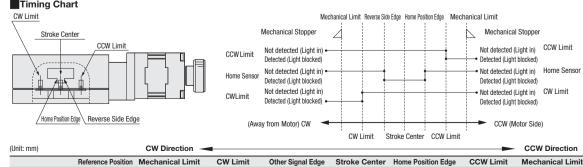
	Connecting	Diagram		D		
1	Motor Lead	Blue \	MOTOR	Brown	\oplus	CWLS
2	Motor Lead	Red L	MOTOIT	Diack	OUT1	
3	Motor Lead	Orange		Blue	OUT2	
4	Motor Lead	Green		Diuc	\ominus	
5	Motor Lead	Black		D		
6	CWLS Output			Brown Black	\oplus	CCWLS
7	CCWLS Output			DIdUK	OUT1	
8	Open			Blue	OUT2	
9	Power Supply (+)			Diuc	\ominus	
10	ORG Output		<u> </u>	D		
	Power Supply (-)		 	Brown	(H)	ORG
12	F.G	\vdash		Black	OUT1	
		-		Dluo	0UT2	

■Electrical Specifications

Dout Number		C	MS			
	Part Number	Standard	Resolution(0.36°)			
	Type	5-Phase Stepping Motor 0.75A/Phase (Oriental Motor Co., Ltd.)				
Motor	Part Number	C005C-90215P-1(28mm)	C7214-9015-1(_38mm)			
	Step Angle	0.72°	0.36°			
	Driver Part Number	-				
	Part Number	HR10A-10J-12P (73) (Hirose Electric Co., LTD.)				
Connector	Applicable Receptacle Connector	HR10A-10P-12S (73) (Hirose Electric Co., LTD.)				
Connector	Contact Part Number	-				
	Applicable Receptacle Contact Part Number	-				
	Limit Sensor	Provided				
	Slit Home Origin Sensor	sor Provided				
	Home Sensor		-			
	Part Number	Photomicrosensor: PM-L25 (Panasonic Industrial Devices SUNX Co.				
Sensor	Power Supply Voltage	DC5~24V or less ±10%				
Selisui	Current Consumption	1 45mA or less (15mA or less per Sensor)				
		NPN Open Collector Output DC30V or less, 50mA or less				
	Control Output	Residual Voltage 2V or less (when load current is 50mA)				
		Residual Voltage 1V or less (when load current is 16mA)				
	Output Logic	Detecting (Dark): Output Transistor OFF (Non-Conducting)				

Sensors with Part Number PM □24 are to be discontinued and replaced by next-generation products with Part Number PM- 25 from April 2017.

Timing Chart



- Thoming Routine Above: When DS102/DS112 Series controller is used and when the Homing Routine Type 3 is executed.
- The coordinates shown are design values. There may be approx. ±0.5mm misalignment on the physical dimensions.
- For details about Homing, see P. 1 -1735-97

1 -2012-9